# M. Straub, **A. Riener**, A. Ferscha Distance Encoding in Vibro-tactile Guidance Cues

#### **MobiQuitous 2009**

Sixth Annual International Conference on Mobile and Ubiquitous Systems
13 - 16 July 2009
Toronto, Ontario, Canada



This work is supported under the FP7 ICT FET programme of the European Commission under grant agreement No 231288 (SOCIONICAL).



## Vibro-tactile Guidance: Problem Statement, Setting

#### Known difficulties of navigation in unfamiliar places or in harsh environments

- Traditional approach: Guidance with visual and/or auditory sensory channels.
- Problems
  - Sensory channels are often overloaded.
  - Physical properties limit perception capabilities (e.g. reflecting light, smoke or fog for the visual channel; plenty of overlayed sources of auditory information).
  - Eyes, ears, and/or hands are inaccessible (used for other tasks).
- Particularly of interest: Disabled (blind) people (cannot unfold a map...).

#### **Hardware setting**

- Vibro-tactile notifications with a "tactor belt" (8 tactile actuators, Ø 30mm, 200 300Hz resonance, 180ms controller latency, Bluetooth connection).
- Wireless ultrasonic position/orientation tracking system (Intersense IS-900).
- Music played via headphones to mask vibration noise.









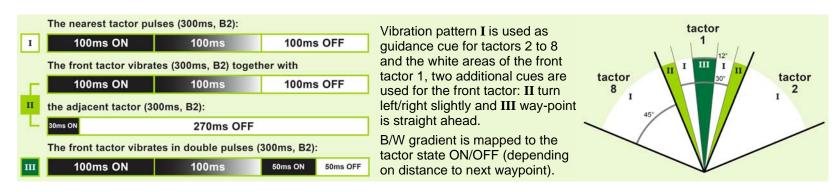
### Vibro-tactile Guidance: User Studies

#### **Experiments**

Variation Parameters (parametrization): (i) vibration intensity (attenuation), (ii) vibration frequency, (iii) vibration mode (tactile patterns or *Tactograms*), defined by pulse-pause times, latency, etc.

#### Different distance encoding schemas

- Basic series (750ms system latency)
  - (A1) Baseline: Fixed frequency (250Hz), fixed attenuation (-0db), sustained vibration.
  - (A2) Distance encoding: Frequency range 200 300Hz, attenuation range -24db to -0db, sustained vibration.
- Advanced series (reduced system latency, 250ms)
  - (B1) Baseline: as above (A1).
  - (B2) Distance encoding: Frequency range 250 320Hz, fixed attenuation (-0db), different *Tactograms* dependent on distance and direction of next waypoint.



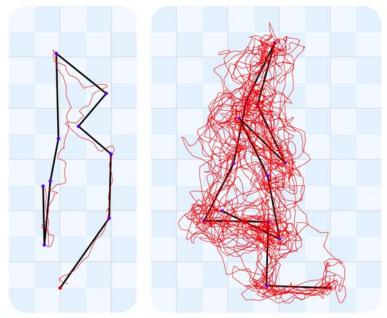
#### Vibro-tactile Guidance: Results and Conclusion

#### Orientation information is important for accurate route-guidance

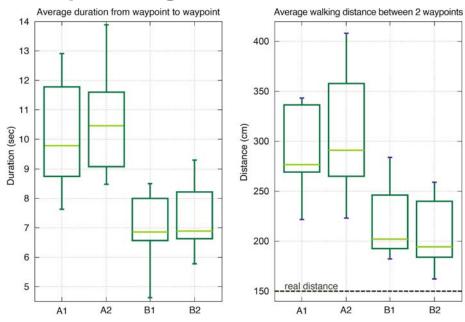
- Test participants were able to follow the waypoints quite well (low variation).
- Distance information does not improve the walking accuracy much (A1, A2).
- System latency directly affects walking performance (A, B series).

#### **Next steps**

- Larger studies with blind people.
- Installation/evaluation of WLAN-based campus navigation.



Trace of one test participant (left) and the overlay of traces from 11 attendees (right) gives an indication on system-performance.



Boxplots shows average duration (left) and walking distance (right) for all of the 4 experiments.